

# Tianxin Tao

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## Education

### University of British Columbia

*B. Applied Science in Mechanical Engineering, minor in Computer Science*

- Average: 89.6%

Vancouver, Canada

Sep. 2014 – May 2019

### University of British Columbia

*Master in Computer Science*

- Supervisor: Prof. Michiel van de Panne
- Average: 95.8%
- Expected Graduation: May, 2022

Vancouver, Canada

Sep. 2019 – Present

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## Publication

### Evaluating Vision Transformer Methods for Deep Reinforcement Learning from Pixels

Tianxin Tao\*, Daniele Reda\*, Michiel van de Panne

(\*: equal contribution)

*Under Review*

### Learning to Get Up

Tianxin Tao, Matthew Wilson, Ruiyu Gou, Michiel van de Panne

*ACM SIGGRAPH 2022*

### Style-ERD: Responsive and Coherent Online Motion Style Transfer

Tianxin Tao, Xiaohang Zhan, Zhongquan Chen, Michiel van de Panne

*IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2022*

### Learning to Locomote: Understanding How Environment Design Matters for Deep Reinforcement Learning

Daniele Reda\*, Tianxin Tao\*, Michiel van de Panne

(\*: Equal Contribution)

*ACM SIGGRAPH Motion, Interaction and Games (MIG 2020)*

### Towards the Development of a Learning-Based Intention Detection Framework for Pushrim-Activated Power-Assisted Wheelchairs

Mahsa Khalili, Tianxin Tao, Ruolan Ye, Shuyong Xie, Huancheng Yang, H.F. Machiel Van der Loos, Jaimie Borisoff

*2019 IEEE-RAS-EMBS International Conference on Rehabilitation Robotics (ICORR)*

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## Experience

### AI Engineer Intern

*2012 Lab (Central Media Institute), Huawei Technologies Co., Ltd.*

- Implemented rule-based motion stylization algorithm based on heuristics
- Re-implemented offline motion stylization algorithms published in SIGGRAPH
- Developed novel neural network architecture for online motion stylization based on LSTM

May 2021 – August 2021

*Shenzhen, China*

### Research Assistant

*IMAGER Lab, University of British Columbia*

Sep 2019 – Present

*Vancouver, BC, Canada*

- Investigated the influence of self-supervised learning objectives with vision transformers on the reinforcement learning from pixels problem (ongoing project)
- Developed a multi-stage learning pipeline to train get-up motion controllers without motion capture data
- Studied the impact of various parameters in simulation for off-policy reinforcement learning
- Experimented with learning latent representation from multi-view imagery by contrastive learning to better serve locomotion tasks in reinforcement learning
- Explored different choices of action space in reinforcement learning for locomotion tasks

**Teaching Assistant** May 2019 – Dec 2020  
*University of British Columbia* *Vancouver, BC, Canada*

- Course instructed: CPSC 121 (Models of Computation), CPSC 314 (Computer Graphics), CPSC 425 (Computer Vision)
- Prepared coding assignments for the courses
- Led labs and tutorial sections to help students better understand the course material

**Technical Assistant** May 2018 – Aug 2018  
*Department of Forest Resources Management, University of British Columbia* *Vancouver, BC, Canada*

- Designed the user interface of the website to support the researchers
- Implemented the front-end interface in ReactJS
- Designed the structure of the database, and implemented user sign up, log in functions using Firebase

## Volunteer

**Student Volunteer** Jan 2020  
*ICML 2020* *Online*

- Organized and invigilated poster discussion on Zoom

**Research Volunteer** May 2017 - August 2017  
*Industrial and Automation Laboratory, University of British Columbia* *Vancouver, BC, Canada*

- Implemented boustrophedon decomposition path planning algorithm
- Built Gazebo simulation to examine the performance of proposed path planning algorithm
- Programmed micro-controller to control the motor speed of a robotic boat

## Awards & Scholarships

**Graduate Teaching Assistant Award** May 2021  
*Computer Science, University of British Columbia*

- Presented to graduate teaching assistants who have distinguished themselves by earning outstanding scores and feedback from students on teaching evaluations.

**Faculty of Applied Science International Student Scholarship** December 2018  
*University of British Columbia*

- Offered to continuing international students in the Faculty of Applied Science who demonstrate strong academic achievement, engagement in the Faculty, and the potential to make a scholarly contribution within their chosen field of study

**Elizabeth and Leslie GOULD Scholarship in Engineering** November 2018  
*University of British Columbia*

- Three scholarships offered to engineering students in the Faculty of Applied Science which are made on the recommendation of the Faculty

**Undergraduate Student Academic Achievement Award** October 2017, November 2018  
*Mechanical Engineering, University of British Columbia*

**The Trek Excellence Scholarship** September 2015, September 2018  
*University of British Columbia*

- Offered to students in the top 5% of their undergraduate year

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## Skills

**Programming Languages:** Python, JavaScript, MATLAB, C++

**Developer Tools:** PyTorch, Git, Mujoco, scikit-learn, Amazon Azure

**Languages:** Chinese, English